

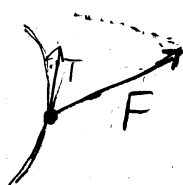
16.9 Divergence Theorem (Gauss's Theorem)REM Green's Theorem

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_D \left(\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA = \iint_D \text{curl}(\vec{F}) dA$$

In lecture notes for 16.5, we recalled that this line integral

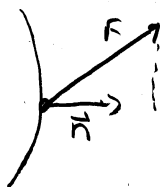
$$\text{is } \oint_C \vec{F} \cdot d\vec{r} = \oint_C \vec{F} \cdot \vec{T} ds, \text{ where } \vec{T} \text{ is the unit tangent}$$

vector.



" $\vec{F} \cdot \vec{T}$ is the amount of \vec{F} in the direction of \vec{T} ."

We then asked if we could glean any interesting information about the vector field by using an outward normal vector in lieu of the unit tangent vector.



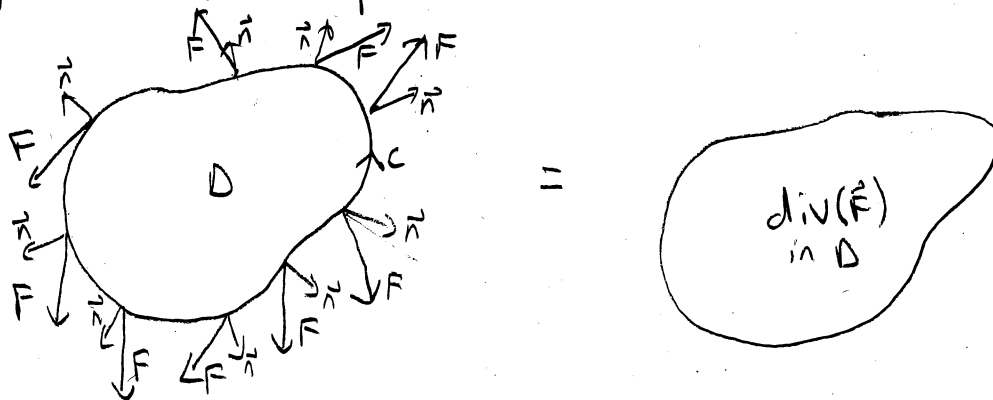
" $\vec{F} \cdot \vec{n}$ is the amount of \vec{F} in the direction of \vec{n} ."

Turns out it does: we can derive the following

$$\oint_C \vec{F} \cdot \vec{n} ds = \iint_D \text{div}(\vec{F}) dA$$

To see this computation, see the beginning of the Lecture #15 notes. It turns out that this is a 2-dimensional version of the Divergence theorem. It says that the amount of

of flow (or flux) leaving a region is the sum of the divergence across the space:



This statement holds in higher dimensions! We state it for dim-3 below:

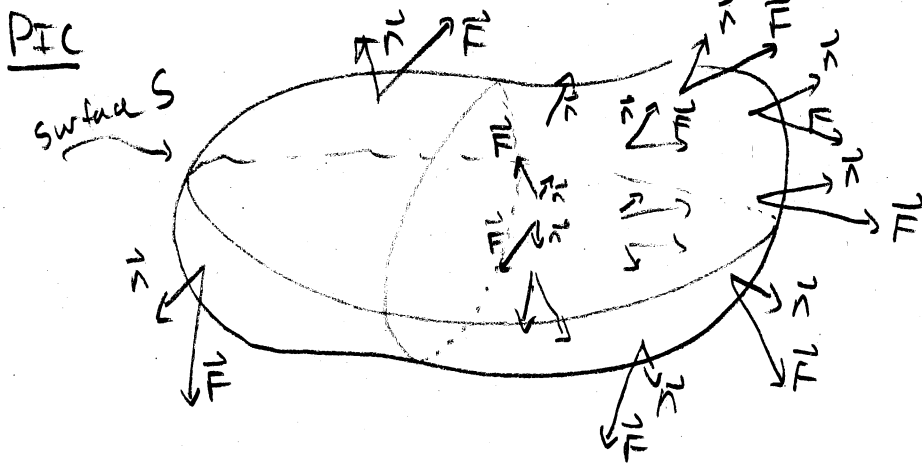
THM (Divergence Theorem)

Let E be a simple solid region and let S be the boundary surface of E , given with positive (outward) orientation. Let \vec{F} be a vector field whose component functions have continuous partial derivatives on an open region that contains E . Then

$$\boxed{\iint_S \vec{F} \cdot \vec{n} \, dS = \iiint_E \operatorname{div}(\vec{F}) \, dV} \quad (*)$$

Remark: Book may write

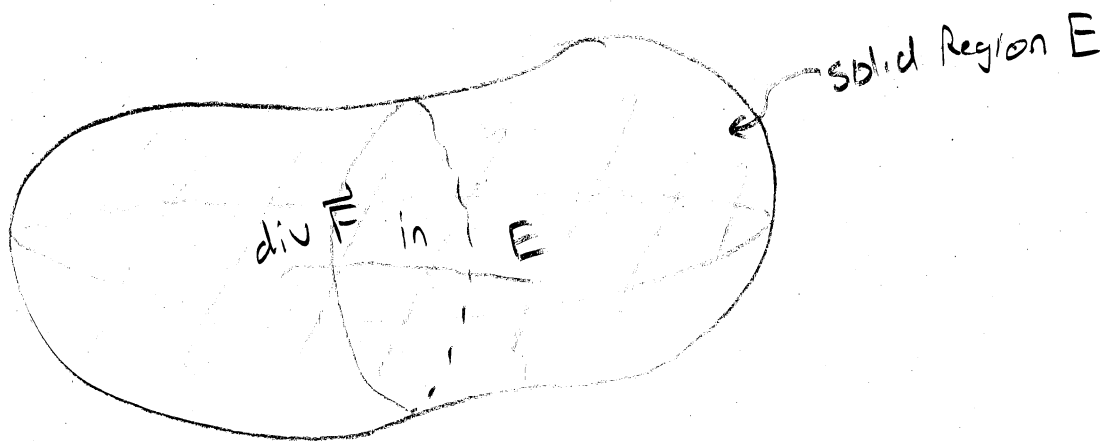
$$\iint_S \vec{F} \cdot \vec{n} \, dS \text{ as } \iint_S \vec{F} \cdot d\vec{S}. \quad \left(\text{Here } d\vec{S} = \vec{n} \, dS \right)$$



"How much is leaving"

"Flux through the surface S"

This is equal to:



REM

Divergence can be thought of in terms of fluid dynamics: the divergence at a point is how much the fluid "diverges" from this point. If the fluid "diverges" at every point in a region (E) , it must leave the region, i.e. pass through the surface (S) of the region.

Proof of Divergence Theorem

Let $\vec{F} = P\hat{i} + Q\hat{j} + R\hat{k}$ and let it have continuous partial derivatives on a ^{open} region containing E .

$$\text{rem } \text{div } \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z}$$

$$\text{so } \iiint_E \text{div}(\vec{F}) dV = \iiint_E \frac{\partial P}{\partial x} dV + \iiint_E \frac{\partial Q}{\partial y} dV + \iiint_E \frac{\partial R}{\partial z} dV.$$

Now, let \vec{n} denote the outward normal on S , the boundary of E , and we see

$$\begin{aligned} \iint_S \vec{F} \cdot \vec{n} dS &= \iint_S (P\hat{i} + Q\hat{j} + R\hat{k}) \cdot \vec{n} dS \\ &= \iint_S P\hat{i} \cdot \vec{n} dS + \iint_S Q\hat{j} \cdot \vec{n} dS + \iint_S R\hat{k} \cdot \vec{n} dS \end{aligned}$$

notice: $P\hat{i} \cdot \vec{n} = \langle P, 0, 0 \rangle \cdot \langle n_1, n_2, n_3 \rangle = Pn_1$
etc.

We show that

$$\iiint_E \frac{\partial P}{\partial x} dV = \iint_S P\hat{i} \cdot \vec{n} dS, \quad (\text{and similarly for the other two terms!})$$

To do this, we will make one additional assumption (the proof becomes much harder if you do not do this!). We

need to assume that E is a nice region, i.e. can

be written as $E := \{(x, y, z) : (y, z) \in D \text{ and } u_1(y, z) \leq x \leq u_2(y, z)\}$,

where $D := \{(y, z) : a \leq z \leq b, f_1(z) \leq y \leq f_2(z)\}$ or $\{(y, z) : a \leq y \leq b, f_1(y) \leq z \leq f_2(y)\}$.

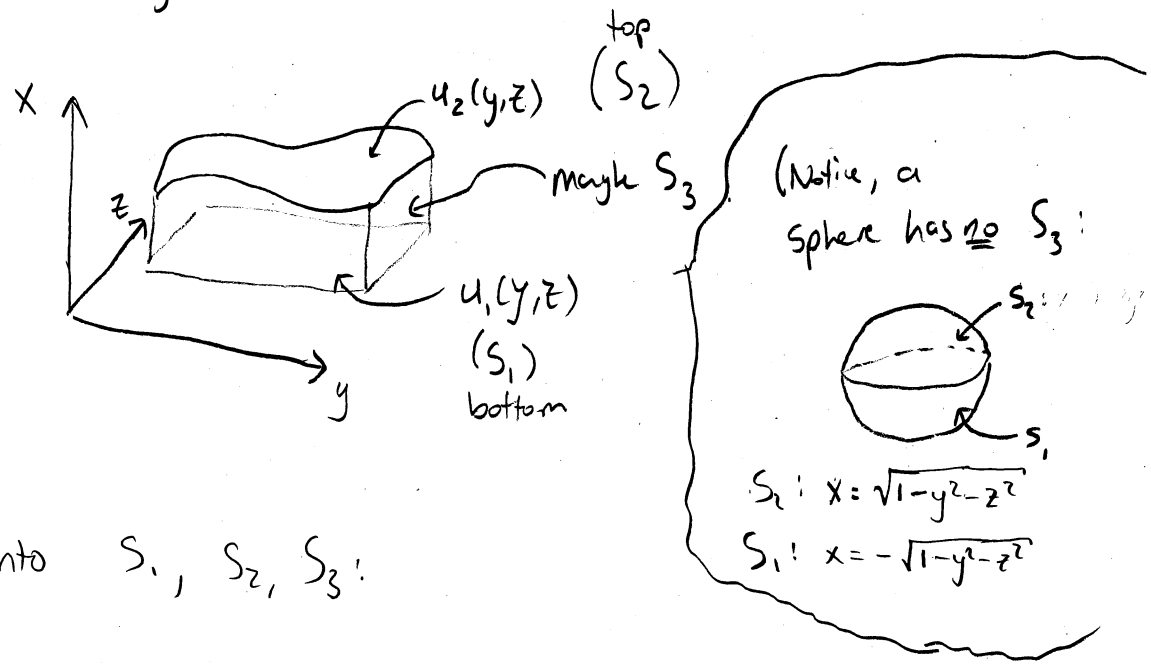
We know from our work with triple integrals that this isn't always possible!

If this is true, then

$$\begin{aligned} \iiint_E \frac{\partial P}{\partial x} dV &= \iint_D \left(\int_{u_1(y,z)}^{u_2(y,z)} \frac{\partial P}{\partial x} dx \right) dA \\ &= \iint_D [P(u_2(y,z), y, z) - P(u_1(y,z), y, z)] dA \end{aligned}$$

Fundamental Theorem of Calculus!

Next, consider $\iint_S P \hat{i} \cdot \vec{n} dS$. The surface will have a top and bottom, and ~maybe a side:



So break S into S_1, S_2, S_3 :

$$\iint_S P \hat{i} \cdot \vec{n} dS = \iint_{S_1} P \hat{i} \cdot \vec{n} dS + \iint_{S_2} P \hat{i} \cdot \vec{n} dS + \iint_{S_3} P \hat{i} \cdot \vec{n} dS$$

If there is an S_3 , notice, because of how our region E is defined

$$\hat{i} \cdot \vec{n} = 0$$

Since \hat{i} points in the x -direction (up in the picture) and \vec{n} must be parallel to the yz -plane. In other words, they are normal vectors, so the dot product is 0.

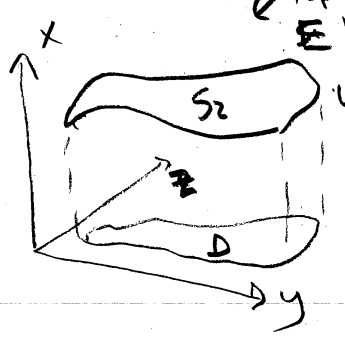
This means

$$\iint_{S_3} P \hat{i} \cdot \vec{n} \, dS = \iint_{S_3} 0 \, dS = 0.$$

Thus,

$$\iint_S P \hat{i} \cdot \vec{n} \, dS = \iint_{S_1} P \hat{i} \cdot \vec{n} \, dS + \iint_{S_2} P \hat{i} \cdot \vec{n} \, dS.$$

Consider



$$\iint_{S_2} P \hat{i} \cdot \vec{n} \, dS = \iint_D \langle P, 0, 0 \rangle \cdot \left\langle 1, \frac{\partial u_2}{\partial y}, \frac{\partial u_2}{\partial z} \right\rangle \, dA$$

this is the parameter domain, same D as before!

$$\vec{n} = \frac{\vec{r}_y \times \vec{r}_z}{|\vec{r}_y \times \vec{r}_z|}$$

(graph of a function!)

$$= \frac{1}{|\vec{r}_y \times \vec{r}_z|} \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial u_2}{\partial y} & 1 & 0 \\ \frac{\partial u_2}{\partial z} & 0 & 1 \end{vmatrix} = 1 \hat{i} + \frac{\partial u_2}{\partial y} \hat{j} + \frac{\partial u_2}{\partial z} \hat{k}$$

So,

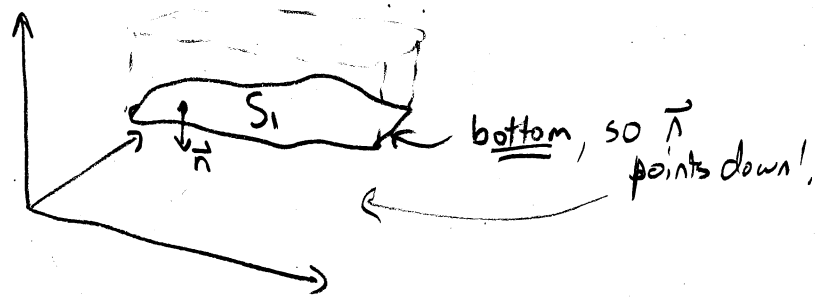
$$\begin{aligned} \iint_{S_2} P \hat{n} \cdot \vec{n} \, dS &= \iint_D P \, dA \quad \leftarrow \text{evaluated at } \begin{cases} x = u_2(y, z) \\ y = y \\ z = z \end{cases} \\ &= \iint_D P(u_2(y, z), y, z) \, dA \end{aligned}$$

Similarly

$$\iint_{S_1} P \hat{n} \cdot \vec{n} \, dS = - \iint_D P \, dA = - \iint_D P(u_1(y, z), y, z) \, dA$$

$$\vec{n} = - \frac{\vec{r}_y \times \vec{r}_z}{|\vec{r}_y \times \vec{r}_z|}$$

* we need to flip the normal vector!



Thus,

$$\iint_S P \hat{n} \cdot \vec{n} \, dS = \iint_D (P(u_2(y, z), y, z) - P(u_1(y, z), y, z)) \, dA$$

which matches our computation for $\iiint_E \frac{\partial P}{\partial x} \, dV$.

The other two terms work similarly!



EXAMPLE 1

Find the flux of the vector field $\vec{F} = z^3 \hat{i} + y \hat{j} + \sin(x) \hat{k}$ over the unit sphere $x^2 + y^2 + z^2 = 1$.

We are being asked to compute $\iint_S \vec{F} \cdot \vec{n} \, dS$, the flux. Notice that

- S is the boundary of a simple solid region $E := \{(x, y, z) : x^2 + y^2 + z^2 \leq 1\}$.
- $\frac{\partial P}{\partial x}, \frac{\partial P}{\partial y}, \frac{\partial P}{\partial z}, \frac{\partial Q}{\partial x}, \frac{\partial Q}{\partial y}, \frac{\partial Q}{\partial z}, \frac{\partial R}{\partial x}, \frac{\partial R}{\partial y}, \frac{\partial R}{\partial z}$ are continuous in E (and actually all of \mathbb{R}^3).

\Rightarrow We can apply the divergence theorem.

$$\iint_S \vec{F} \cdot \vec{n} \, dS = \iiint_E \operatorname{div}(\vec{F}) \, dV$$

$$\operatorname{div} \vec{F} = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = 0 + 1 + 0 = 1, \quad \begin{array}{l} \frac{4\pi r^3}{3} \\ \downarrow \end{array}$$

Thus $\iint_S \vec{F} \cdot \vec{n} \, dS = \iiint_E 1 \, dV = \iiint dV = V(\text{unit sphere}) = \frac{4\pi(1)^3}{3}$

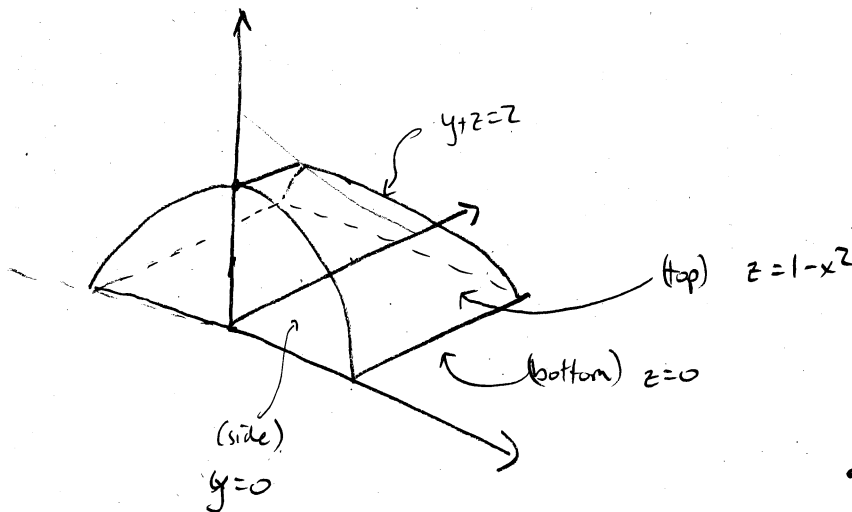
$$\boxed{= \frac{4\pi}{3}}$$

EXAMPLE 2

Evaluate $\iint_S \vec{F} \cdot d\vec{s}$, where

$$\vec{F}(x,y,z) = xy\hat{i} + (y^2 + e^{xz^2})\hat{j} + \sin(xy)\hat{k}$$

and S is the surface of the region E bounded by the parabolic cylinder $z=1-x^2$ and the planes $z=0$, $y=0$, and $y+z=2$.



- S is the boundary of a simple solid region
-

Use Divergence Theorem!

$$\iint_S \vec{F} \cdot d\vec{s} = \iiint_E \text{div}(\vec{F}) dV$$

$$\text{div}(\vec{F}) = \frac{\partial P}{\partial x} + \frac{\partial Q}{\partial y} + \frac{\partial R}{\partial z} = y + 2y + 0 = 3y$$

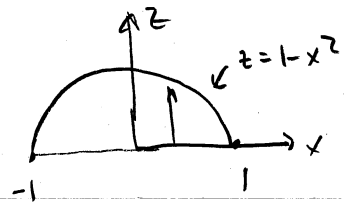
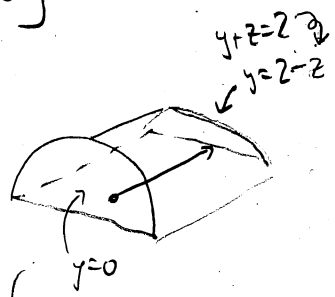
$$= \iiint_E 3y dV$$

integrate w.r.t y first

$$= \int \int 3y dV$$

integrate z next

$$= \int_{-1}^1 \int_0^{1-x^2} \int_0^{2-z} 3y dy dz dx$$



$$= 3 \int_{-1}^1 \int_0^{1-x^2} \left[\frac{y^2}{2} \right]_0^{2-z} dz dx$$

$$= \frac{3}{2} \int_{-1}^1 \int_0^{1-x^2} (2-z)^2 dz dx$$

$$= \frac{3}{2} \int_{-1}^1 \left[-\frac{(2-z)^3}{3} \right]_0^{1-x^2} dx$$

\downarrow $u = 2-z$
 $du = -1 \cdot dz$

$$= \frac{1}{2} \int_{-1}^1 (-(2-(1-x^2))^3 + 8) dx$$

$$= -\frac{1}{2} \int_{-1}^1 ((1+x^2)^3 - 8) dx$$

$$= -\frac{1}{2} \int_{-1}^1 [(1+x^2)(1+2x^2+x^4) - 8] dx$$

$$= -\frac{1}{2} \int_{-1}^1 [1+2x^2+x^4+x^2+2x^4+x^6 - 8] dx$$

$$= -\frac{1}{2} \int_{-1}^1 (3x^2 + 3x^4 + x^6 - 7) dx$$

$$= -\frac{1}{2} \left[x^3 + \frac{3x^5}{5} + \frac{x^7}{7} - 7x \right]_{-1}^1$$

$$= -\frac{1}{2} \left[\left(1 + \frac{3}{5} + \frac{1}{7} - 7 \right) - \left(-1 + \frac{-3}{5} + \frac{-1}{7} + 7 \right) \right]$$

$$= -\frac{1}{2} \left[2 + \frac{6}{5} + \frac{2}{7} - 14 \right] = -\frac{1}{2} \left[\frac{70}{35} + \frac{42}{35} + \frac{10}{35} - \frac{490}{35} \right]$$

$$= \frac{184}{35}$$