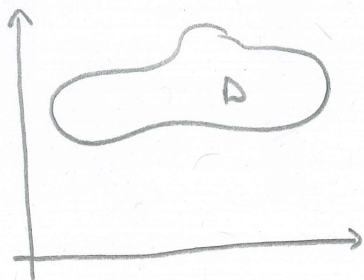


15.4 Applications of Double Integrals

Say we have a region in the plane that is representative of a (flat) object:

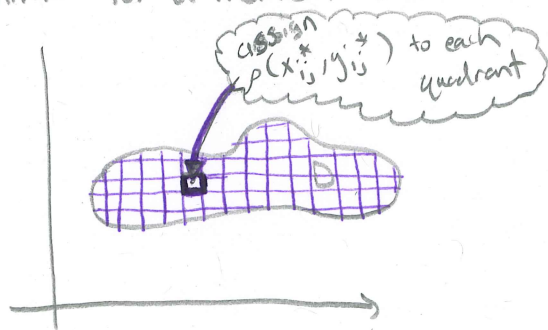


- We could compute the area of this region, $\iint_D dA$, giving us something in "units squared." Assume for a moment that our units are meters, so m^2 is the unit for the area.
- If we had a "density" function, $\rho(x,y)$, which gives us the density at each point in D , we could compute the mass.

RECALL: Area \cdot density = mass
 $(m^2 \cdot kg/m^2 = kg)$

NOTE In the above formula, density may be referred to as an "area density".

- Now, think for a moment about Riemann Sums:



$$m = \lim_{k, l \rightarrow \infty} \sum_{i=1}^k \sum_{j=1}^l \underbrace{\rho(x_{ij}^*, y_{ij}^*)}_{\text{density}} \cdot \underbrace{\Delta x \Delta y}_{\text{area}}$$

QUESTION

Given any region D with some area-density function $\rho(x,y)$, we can compute the total mass. Can we find the center of mass? In other words, where could we put our finger to balance the flat plate D :



We can compute this point! However, we will need some definitions first.

DEF Moment about the x -axis

$$M_x = \iint_D y \rho(x,y) dA$$

DEF Moment about the y -axis

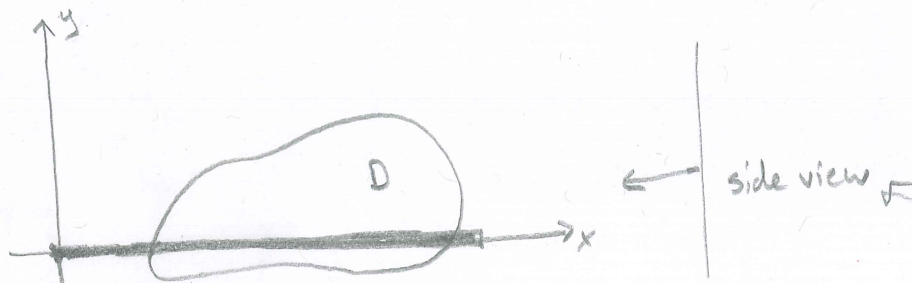
$$M_y = \iint_D x \rho(x,y) dA$$

QUESTION

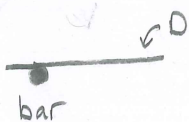
What are these moments? Is there some intuition underlying these objects?

INTERPRETATION 1

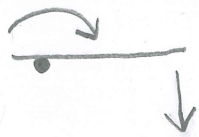
consider M_x , moment about the x -axis. Imagine a bar beneath the region D along the x -axis:



How "unbalanced" is D on this bar. Consider a side view.



Notice that if more mass is on one side of the bar, there is an immediate "tendency" for D to fall in that direction. In the moment the fall begins, we can think of this as a rotation about the bar, or a rotation about the x -axis.



M_x is giving you some indication as to how quickly D will fall over one side or the other of the bar (or x -axis).

QUESTION Why does M_x have a "y" in the integral?

Because the further the mass is from the x -axis (which is the y -coordinate!) the faster it wants to rotate about the x -axis!

Then, we can interpret M_y the same way, except instead of a "rotation" about the x -axis, it is measuring some tendency to "rotate" about the y -axis.

INTERPRETATION 2

Consider the Riemann sum whose limit is M_x :

$$\sum y^* \cdot \rho(x^*, y^*) \cdot \Delta x \Delta y \longrightarrow \iint_D y \rho(x, y) dA$$

REM $\iint_D \rho(x, y) dA = \text{mass} = m$

Consider dividing this Riemann sum by the mass m :

$$\frac{1}{m} \left(\sum y^* \cdot \rho(x^*, y^*) \Delta x \Delta y \right)$$

What we have written is a "weighted average", i.e.

the average weighted by the y -coordinate.

We can interpret M_y similarly.

Now we can define the center of mass:

DEF Center of mass, (\bar{x}, \bar{y})

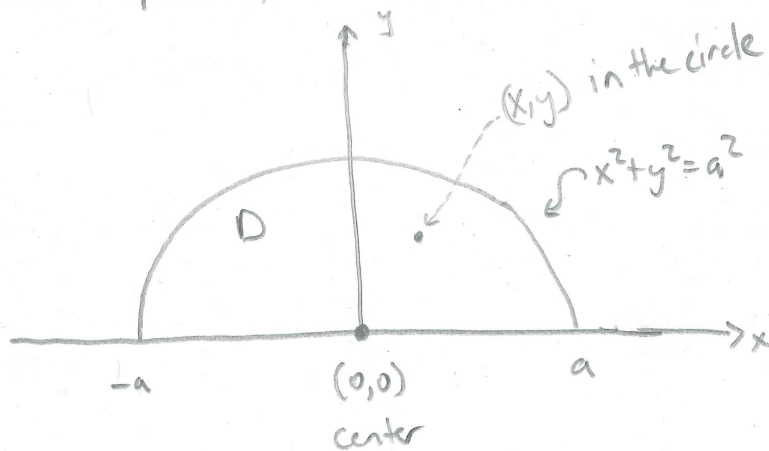
$$\bar{x} = \frac{M_y}{m} = \frac{1}{m} \iint_D x \rho(x,y) dA$$
$$\bar{y} = \frac{M_x}{m} = \frac{1}{m} \iint_D y \rho(x,y) dA,$$

where m is the mass.

REMARK Notice that we are scaling the moment by mass!

EXAMPLE Consider the upper half of the circle $x^2 + y^2 = a^2$. Assume the density at any point in the half circle is proportional to the distance from the center of the circle. Find the center of mass.

STEP 1: Draw a picture!



STEP 2: Interpret the sentence about the density.

- Distance to the center for any (x,y) in our region:

$$d(x,y) = \sqrt{x^2 + y^2}$$

- Density is proportional to distance, so

our density function is

$$\rho(x,y) = K \cdot d = K \sqrt{x^2+y^2}$$

STEP 3: Compute the mass.

$$\begin{aligned} m &= \iint_D \rho(x,y) dA = \iint_D K \sqrt{x^2+y^2} dA \\ &= \int_{\theta=0}^{\pi} \int_{r=0}^a (Kr) \underbrace{r dr d\theta}_{\substack{\text{use polar!} \\ r^2 = x^2+y^2 \\ r = \sqrt{x^2+y^2}}} \\ &= \int_0^{\pi} \int_0^a Kr^2 dr d\theta \\ &= \int_0^{\pi} \left[\frac{K}{3} r^3 \right]_0^a d\theta \\ &= \frac{Ka^3}{3} \int_0^{\pi} d\theta \\ &= \frac{Ka^3}{3} \cdot [\theta]_0^{\pi} \\ &= \boxed{\frac{K\pi a^3}{3}} \end{aligned}$$

STEP 4: Compute \bar{x} .

(Exercise! This is 0. Can you go back to the statement of the problem, and see why \bar{x} should be 0?)

STEP 5: Compute \bar{y} .

pdar! $y = r \sin \theta$, $p(x,y)$ as before

$$\begin{aligned}\bar{y} &= \frac{1}{m} \iint_D y \cdot p(x,y) dA = \frac{3}{K\pi a^3} \int_0^\pi \int_0^a (r \sin \theta) \cdot (Kr) \cdot \sqrt{dA} \\ &= \frac{3}{\pi a^3} \int_0^\pi \int_0^a r^3 \sin \theta dr d\theta \\ &= \frac{3}{\pi a^3} \int_0^\pi \left[\frac{r^4}{4} \right]_0^a \cdot \sin \theta d\theta \\ &= \frac{3}{\pi a^3} \int_0^\pi \frac{a^4}{4} \sin \theta d\theta \\ &= \frac{3a}{4\pi} \int_0^\pi \sin \theta d\theta \\ &= \frac{3a}{4\pi} [-\cos \theta]_0^\pi \\ &= \frac{3a}{4\pi} [-(-1) - (-1)] \\ &= \frac{3a}{4\pi} \cdot 2 \\ &= \frac{3a}{2\pi}\end{aligned}$$

So, we can conclude the center of mass is

$$(\bar{x}, \bar{y}) = \left(0, \frac{3a}{2\pi} \right).$$

REMARK

In mechanics courses, you will also see a "moment of inertia" which is a "second moment".

DEF (Moment of Inertia about the x-axis)

$$I_x = \iint_D y^2 \rho(x,y) dA$$

DEF Moment of Inertia about the y-axis:

$$I_y = \iint_D x^2 \rho(x,y) dA$$

And, we can define a moment of inertia about the origin:

DEF Moment of Inertia about the origin

$$I_o = I_x + I_y$$
$$I_o = \iint_D (x^2 + y^2) \rho(x,y) dA$$

EXERCISES

- ① Work example 4 in section 15.4 (8th edition)
- ② Read about Radius of Gyration (15.4 8th edition)