

1. (10 points) Solve the system of linear equations.

$$-2x_1 + 3x_2 + 7x_3 - 11x_4 = -3$$

$$x_1 - 2x_3 + x_4 = 3$$

$$x_1 - x_2 - 3x_3 + 4x_4 = 2$$

Give two different particular solutions to the linear system.

Form the augmented matrix and perform Gauss-Jordan elimination:

$$[A | \mathbf{b}] = \left[\begin{array}{cccc|c} -2 & 3 & 7 & -11 & -3 \\ 1 & 0 & -2 & 1 & 3 \\ 1 & -1 & -3 & 4 & 2 \end{array} \right] \\ \sim \left[\begin{array}{cccc|c} 1 & 0 & -2 & 1 & 3 \\ 0 & 1 & 1 & -3 & 1 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

This matrix is in reduced echelon form, so x_3 and x_4 are free variables and the general solution is

$$x_1 = 2x_3 - x_4 + 3$$

$$x_2 = -x_3 + 3x_4 + 1$$

$$x_3 = x_3$$

$$x_4 = x_4$$

There are many correct choices for the two particular solutions.

For example, taking $x_3 = x_4 = 0$ gives $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 3 \\ 1 \\ 0 \\ 0 \end{bmatrix}$ and taking $x_3 = 1, x_4 = 0$ gives $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \\ 1 \\ 0 \end{bmatrix}$.

2. (10 points) Find all values of x such that $\text{span}\{\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3\} = \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$ where

$$\mathbf{v}_1 = \begin{bmatrix} 3 \\ 2 \\ -3 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \quad \text{and} \quad \mathbf{v}_3 = \begin{bmatrix} 2 \\ x \\ -5 \end{bmatrix}.$$

By Theorem 2.7, it is enough to have $\mathbf{v}_3 \in \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

By Theorem 2.6, this is equivalent to the consistency of the linear system represented by the augmented matrix $[\mathbf{v}_2 \ \mathbf{v}_1 \ | \ \mathbf{v}_3]$.

Form the augmented matrix and perform Gaussian elimination:

$$\begin{aligned} [\mathbf{v}_2 \ \mathbf{v}_1 \ | \ \mathbf{v}_3] &= \left[\begin{array}{cc|c} 1 & 3 & 2 \\ -2 & 2 & x \\ 1 & -3 & -5 \end{array} \right] \\ &\sim \left[\begin{array}{cc|c} 1 & 3 & 2 \\ 0 & -6 & -7 \\ 0 & 0 & 3x-16 \end{array} \right] \end{aligned}$$

This system is consistent only when $3x - 16 = 0$, or $x = 16/3$.

3. (10 points) Determine whether the following set of vectors is linearly independent or linearly dependent. If the set is linearly dependent, express one of the vectors as a linear combination of the others.

$$\mathbf{u}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ 1 \end{bmatrix}, \quad \mathbf{u}_2 = \begin{bmatrix} -2 \\ 3 \\ -3 \\ -3 \end{bmatrix}, \quad \mathbf{u}_3 = \begin{bmatrix} -5 \\ 7 \\ -8 \\ -7 \end{bmatrix}, \quad \text{and} \quad \mathbf{u}_4 = \begin{bmatrix} 3 \\ -4 \\ 6 \\ 4 \end{bmatrix}.$$

Form the matrix $A = \begin{bmatrix} 1 & -2 & -5 & 3 \\ -1 & 3 & 7 & -4 \\ 1 & -3 & -8 & 6 \\ 1 & -3 & -7 & 4 \end{bmatrix}$.

The vectors $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ and \mathbf{u}_4 are linearly independent if and only if the equation $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.

Form the augmented matrix and perform Gauss-Jordan elimination:

$$[A | \mathbf{0}] = \left[\begin{array}{cccc|c} 1 & -2 & -5 & 3 & 0 \\ -1 & 3 & 7 & -4 & 0 \\ 1 & -3 & -8 & 6 & 0 \\ 1 & -3 & -7 & 4 & 0 \end{array} \right] \\ \sim \left[\begin{array}{cccc|c} 1 & 0 & 0 & -1 & 0 \\ 0 & 1 & 0 & 3 & 0 \\ 0 & 0 & 1 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

This matrix is in reduced echelon form, so x_4 is a free variable. Thus there are many nontrivial solutions and the vectors $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ and \mathbf{u}_4 are linearly dependent.

The general solution is

$$\begin{aligned} x_1 &= x_4 \\ x_2 &= -3x_4 \\ x_3 &= 2x_4 \\ x_4 &= x_4 \end{aligned}$$

Take, for example, $x_4 = 1$ to get the particular solution $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ -3 \\ 2 \\ 1 \end{bmatrix}$.

This means that $\mathbf{u}_1 - 3\mathbf{u}_2 + 2\mathbf{u}_3 + \mathbf{u}_4 = \mathbf{0}$ so we can easily solve for \mathbf{u}_1 .

$$\mathbf{u}_1 = 3\mathbf{u}_2 - 2\mathbf{u}_3 - \mathbf{u}_4$$

4. (10 points) Find a 3×5 matrix A , in *reduced* echelon form, with free variables x_3 and x_5 , such that

$$\text{the general solution of the equation } \mathbf{Ax} = \begin{bmatrix} 2 \\ -1 \\ 4 \end{bmatrix} \text{ is } \mathbf{x} = \begin{bmatrix} 2 \\ -1 \\ 0 \\ 4 \\ 0 \end{bmatrix} + s \begin{bmatrix} 2 \\ -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \\ 5 \\ 1 \end{bmatrix},$$

where s and t are real numbers.

Take $x_3 = s$ and $x_5 = t$. Then the general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 2 \\ -1 \\ 0 \\ 4 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} 2 \\ -3 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} 0 \\ 1 \\ 0 \\ 5 \\ 1 \end{bmatrix} = \begin{bmatrix} 2x_3 + 2 \\ -3x_3 + x_5 - 1 \\ x_3 \\ 5x_5 + 4 \\ x_5 \end{bmatrix}$$

Working backward, this comes from the augmented matrix

$$[A | \mathbf{b}] = \left[\begin{array}{ccccc|c} 1 & 0 & -2 & 0 & 0 & 2 \\ 0 & 1 & 3 & 0 & -1 & -1 \\ 0 & 0 & 0 & 1 & -5 & 4 \end{array} \right]$$

Thus

$$A = \begin{bmatrix} 1 & 0 & -2 & 0 & 0 \\ 0 & 1 & 3 & 0 & -1 \\ 0 & 0 & 0 & 1 & -5 \end{bmatrix}$$

5. (10 points) Find a linear transformation $T : \mathbb{R}^2 \rightarrow \mathbb{R}^3$ such that

$$T\left(\begin{bmatrix} 3 \\ -2 \end{bmatrix}\right) = \begin{bmatrix} 4 \\ 1 \\ -7 \end{bmatrix}, \quad T\left(\begin{bmatrix} -1 \\ 1 \end{bmatrix}\right) = \begin{bmatrix} -3 \\ 0 \\ 2 \end{bmatrix} \quad \text{and} \quad T\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}\right) = \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$$

or explain why such a linear transformation cannot exist.

$$\text{Let } \mathbf{v}_1 = \begin{bmatrix} 3 \\ -2 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix} \quad \text{and} \quad \mathbf{v}_3 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}.$$

First check if $\mathbf{v}_3 \in \text{span}\{\mathbf{v}_1, \mathbf{v}_2\}$.

Form the augmented matrix and perform Gauss-Jordan elimination:

$$\begin{aligned} [\mathbf{v}_2 \ \mathbf{v}_1 \mid \mathbf{v}_3] &= \left[\begin{array}{cc|c} -1 & 3 & 1 \\ 1 & -2 & 0 \end{array} \right] \\ &\sim \left[\begin{array}{cc|c} 1 & 0 & 2 \\ 0 & 1 & 1 \end{array} \right] \end{aligned}$$

Thus $\mathbf{v}_3 = 2\mathbf{v}_2 + \mathbf{v}_1$. (This can also be seen just by inspection.)

Such a linear transformation cannot exist, because

$$T(2\mathbf{v}_2 + \mathbf{v}_1) = T(\mathbf{v}_3) = \begin{bmatrix} -2 \\ 1 \\ 3 \end{bmatrix}$$

but

$$2T(\mathbf{v}_2) + T(\mathbf{v}_1) = 2 \begin{bmatrix} -3 \\ 0 \\ 2 \end{bmatrix} + \begin{bmatrix} 4 \\ 1 \\ -7 \end{bmatrix} = \begin{bmatrix} -2 \\ 1 \\ -3 \end{bmatrix}$$